

**Group number: DEC1710**  
**Project title: Autonomous Vehicle Processor**  
**Client &/Advisor: Zambreno/Jones**  
**Team Members/Role:**  
**Alex Orman - Team Leader**  
**Chris Kelley - webmaster**  
**Evan Lambert - Team Key Concept Holder**  
**Lixing Liu - Team Key Concept Holder**  
**Sean Jellison - Communication Leader**  
**Lucas Ince - Scribe**

○ **Weekly Summary (Short summary about what you did this week)**

We meet once this week, discussed which problem suggested by the client we'd like to work on. We settled on identifying ground features as our goal. We came up with a number of tasks to accomplish for the coming week, and divided them out amongst the team.

○ **Individual contributions**

<b><u>NAME</u></b>	<b><u>Individual Contributions</u></b>	<b><u>Hours this week</u></b>	<b><u>HOURS cumulative</u></b>
Alex Orman	Watched Udacity course recommended by Dr.Jones, played with TensorFlow application	3	4
Lixing Liu	Search some cameras	1.5	3
Chris Kelley	Watched Udacity course recommended by Dr.Jones, went to group 1709 meetings, looked at cameras	2.5	4.5
Sean Jellison	Looked into cameras, researched Tensorflow	2	4
Evan Lambert	Created a basic neural network and went to group meetings	3	6
Lucas Ince	Created a basic neural network with tensorflow and went to group meetings	4	5

○ **Plan for coming week (please describe as what, who, when)**

- Alex Orman: Modify TensorFlow tutorial to learn ground features. Post something to git for group
- Lixing Liu: Familiar with TensorFlow and continue cameras part.
- Chris Kelley : meet with client after our advisors. Continue camera research.
- Sean Jellison: Get Tensorflow running and become familiar with the environment.
- Evan Lambert: Learn more about Tensorflow or other libraries.
- Lucas Ince: Learn more about Tensorflow generate test images.